# Two Major Rendering Methods: Rasterization and Ray Tracing

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Course URL: http://jupiter.kaist.ac.kr/~sungeui/SGA/



### At the Previous Class

- The overview of the course
  - Main theme: designing scalable graphics/geometric algorithms
  - Course policy: student presentations and a report at a chosen topic



## What is Rendering?

A process that draws an image from model descriptions



Computer vision inverts the process



# **Physically-based Rendering**

 Generate photo-realistic images based on reality, more precisely, physics



hof.povray.org



# Two Major Rendering Techniques

#### Ray tracing

- Main engine for global illumination
- Used for high quality image generations for movies, architectures, etc.

#### Rasterization

- Simplified rendering method based on local illumination
- Used for interactive rendering for games
- Accelerated with hardware due to the simplicity of the method



### **Local illumination**

- Compute the colors of points on surfaces by considering only local properties
  - Position of the point
  - Surface properties
  - Properties of any light sources that affect it
- No other objects in the scene are considered neither as light blockers nor as reflectors
- Used in OpenGL and DirectX





### **Global Illumination**

- In the real world, light takes indirect paths
  - Light reflects off of other materials (possibly multiple objects)
  - Light is blocked by other objects
  - Light can be scattered
  - Light can bend
- Harder to model
  - At each point we must consider not only every light source, but and other point that might have reflected light toward it



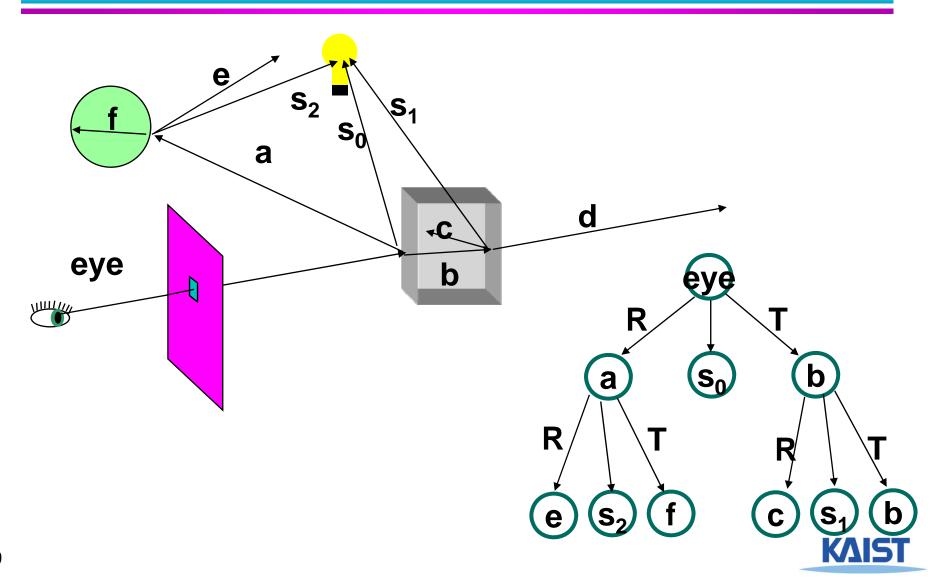


# **Basic Ray Tracing**

- Basic Idea [Whitted 80]
  - Cast a ray into the scene from eye through pixels
  - Computer a first-intersection and recursively construct reflected/shadow/refracted rays
- Isn't this backwards?
  - Light goes from the light sources to the eye
  - Why go the other way?
- Ray tracing minus secondary rays usually called "ray casting"



# **Ray Tree**



### **Acceleration Methods**

- Render time for a ray tracer depends on the number of ray intersection tests per pixel
  - Roughly dependent on the number of primitives in the scene times the number of pixels
- Early efforts focused on accelerating the rayobject intersection tests
- More advanced methods required to make ray Toy RayTracer

tracing practical

- Bounding volume hierarchy
- Spatial partitioning hierarchy



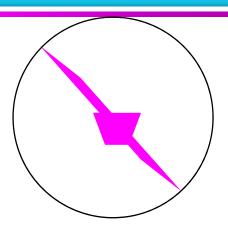
## **Bounding Volumes**

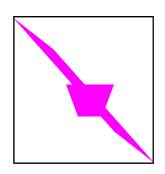
- Enclose complex objects within a simple-tointersect object
  - If the ray does not intersect the simple object then its contents can be ignored
  - The likelihood that it will strike the object depends on how tightly the volume surrounds the object.
- Spheres are simple, but not tight
- Axis-aligned bounding boxes often better



## **Bounding Volumes**

- Sphere [Whitted80]
  - Cheap to compute
  - Cheap test
  - Potentially very bad fit
- Axis-aligned bounding box
  - Very cheap to compute
  - Cheap test
  - Tighter than sphere

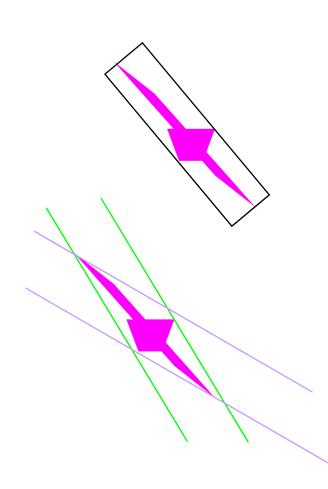






# **Bounding Volumes**

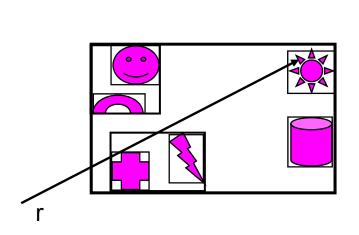
- Oriented Bounding Box
  - Fairly cheap to compute
  - Fairly cheap test
  - Generally fairly tight
- Slabs / K-dops
  - More expensive to compute
  - Fairly cheap test
  - Can be tighter than OBB

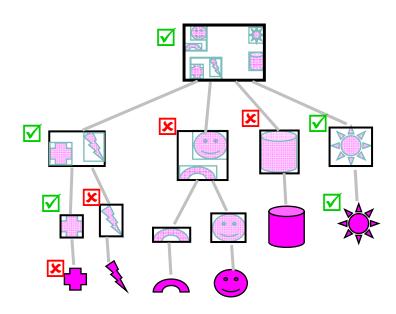




### **Bounding Volume Hierarchy**

- Organize bounding volumes as a tree
- Each ray starts with the scene BV and traverses down through the hierarchy



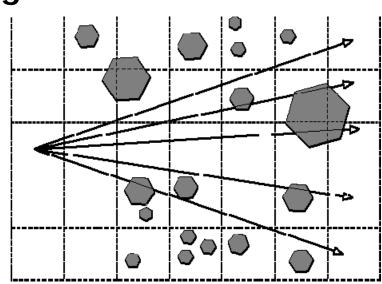




# **Spatial Partitioning Hierarchy**

#### Idea: Divide space to sub-regions

- Place objects within a sub-region into a list
- Only traverse the lists of sub-regions that the ray passes through
- "Mail-boxing" used to avoid multiple test with objects in multiple regions
- Many types
  - Regular grid
  - Octree
  - BSP tree
  - kd-tree

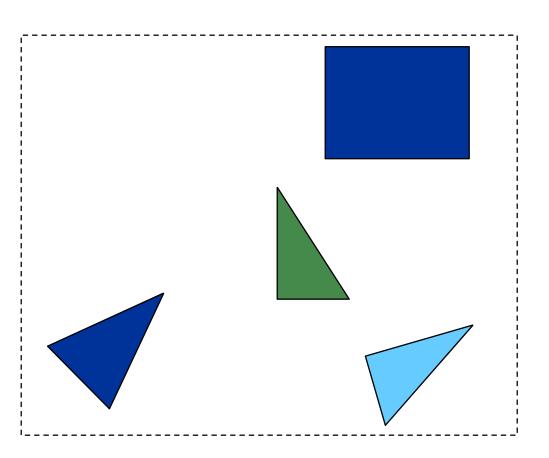




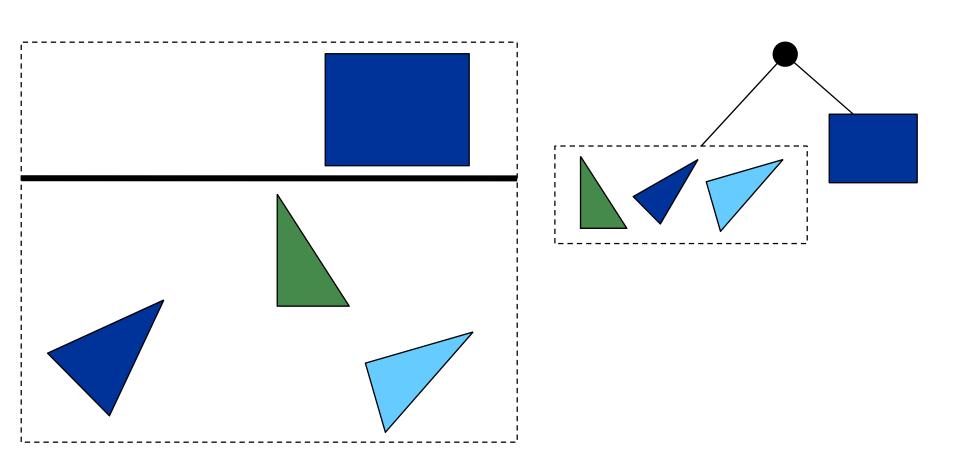
#### kd-trees: overview

- Binary spatial subdivision (special case of BSP tree)
  - Split planes aligned on main axes
  - Inner nodes: subdivision planes
  - Leaf nodes: triangle(s)

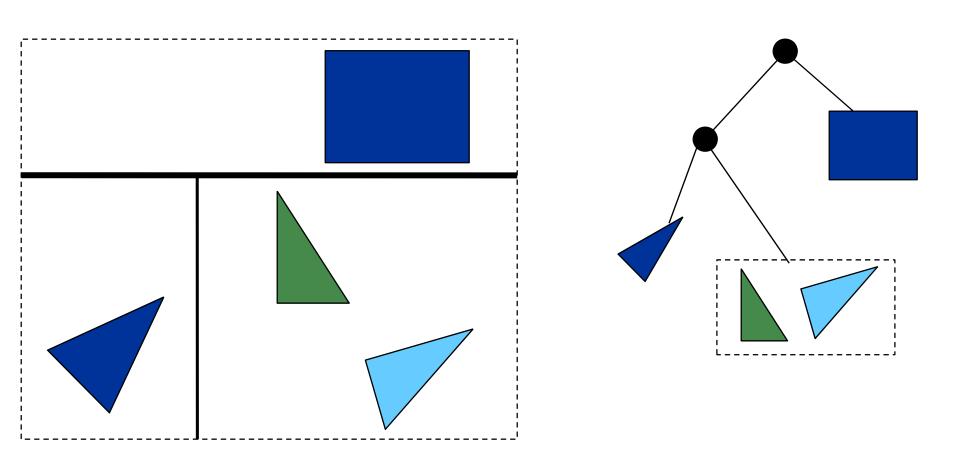




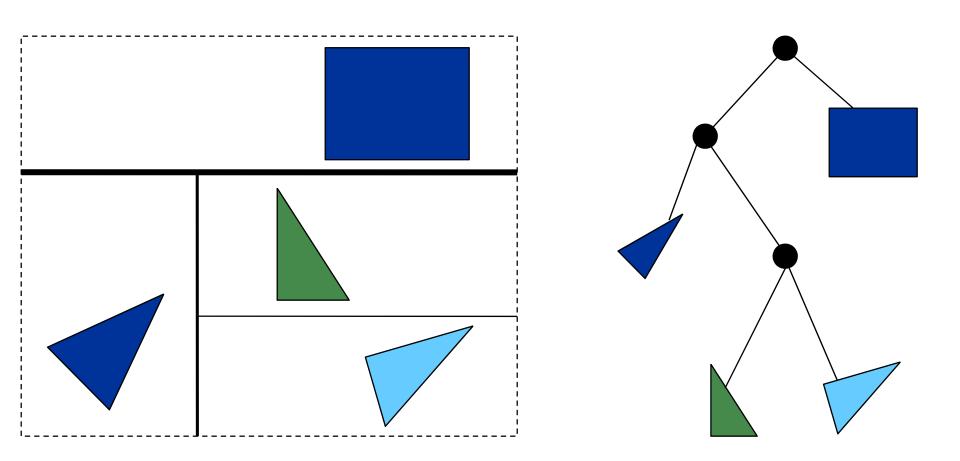




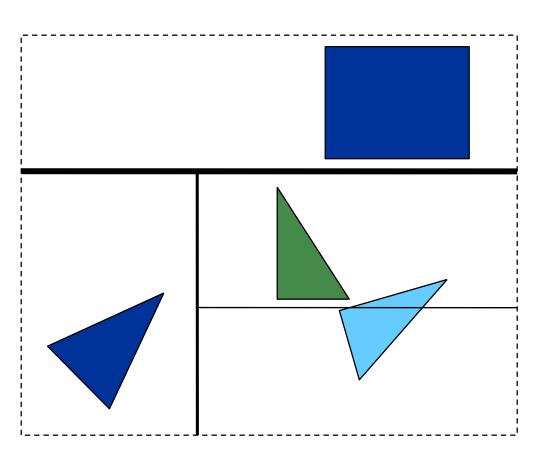






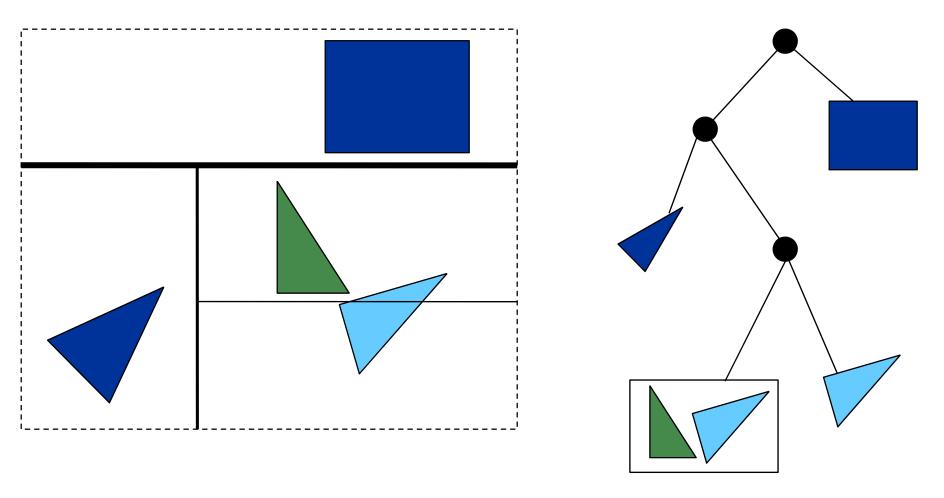






What about triangles overlapping the split?





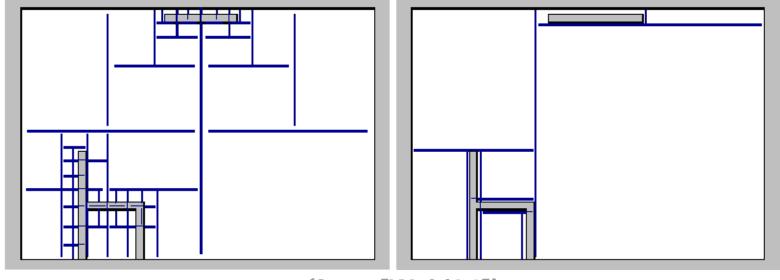


### kd-tree: split planes

- How to select axis & split plane?
  - Largest dimension, subdivide in middle
  - More advanced: surface area heuristic [Goldsmith and Salmon 87] and other improvements [Reshetov05]
- Makes large difference
  - 50%-100% higher overall speedup [Wald04]



### kd-tree: median vs. SAH



(from [Wald04])



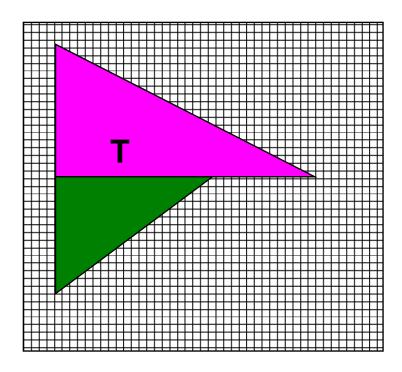
### Ray Tracing with the kd-tree

- Goal: find closest hit with scene
- Traverse tree front to back (starting from root)
- At each node:
  - If leaf: intersect with triangles
  - If inner: traverse deeper



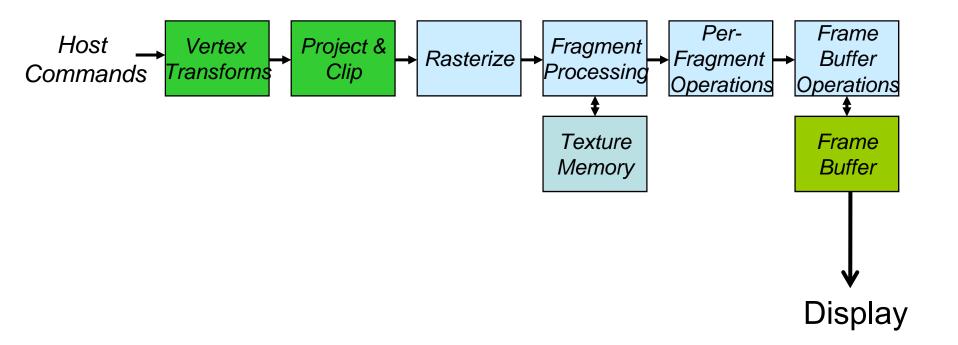
### Rasterization

- Standard method for rendering
- Draw all triangles on a raster:





### Rasterization: Rendering Pipeline





### Rasterization

- Advantage:
  - Use graphics hardware / GPUs (fast, growing even above Moore's Law)
  - 1-2 orders of magnitude faster than ray tracing
- Disadvantages:
  - Local illumination
  - Performance ~ linear to # triangles: can we do better?



#### **Data Access Pattern**

- Streaming or sequential accesses for rasterization
  - Object-driven
- Random access for ray tracing
  - Image-driven
  - Can we make ray tracing to have streaming data access pattern?



### What are Issues?

- Massive models
  - Hierarchy can take very large (memory and disk) space
- Many lights
  - Performance can linearly grow as the number of lights
- Dynamic models
  - Need to update hierarchy
  - Which one is better between BVH or SPH?
- Controllability
  - Can we trade the quality and performance?



#### Homework

- Start choosing a topic that is most interesting to you!
  - You can bring your own research to the course
- Reference
  - Course homepage
  - SIGGRAPH and other papers
  - Refer paper collections in the homepage
  - Google scholar



### Next Time...

- Study culling techniques
  - E.g., visibility culling

